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ANALYSIS OF CLOUD BIOMEDICAL HEALTHCARE SYSTEMS SECURITY BASED ON MATRIX REWRITING SRNS WITH FUZZY PARAMETERS

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Abstract. This paper presents an analytical uncertainty performability, (especially the security) analysis of Cloud Biomedical Healthcare Systems (CBHS) Security based on Matrix Rewriting Stochastic Reward Nets with Fuzzy parameters (FMRSRN), that allows the compact modeling and evaluation of the impact in which is used a proactive defense time-based Moving Target Defense (MTD) technique. A numerical case study for performability modeling and analysis of a particular CBHS is given to show the effectiveness of proposed method.

Keywords: *cloud biomedical healthcare systems security; fuzzy numbers; moving target defense; performability modeling; rewriting rules; stochastic Petri nets.*

Rezumat. Această lucrare prezintă o analiză a performabilității (în special a securității) în condiții de incertitudine a securității sistemelor biomedicale de sănătate implementate în cloud (CBHS) bazată pe rețele stocastice cu recompensă cu parametri fuzzy (FMRSRN), care permite modelarea compactă și evaluarea impactului utilizării unei tehnici de apărare proactivă bazate pe deplasarea în timp a țintelor mobile (MTD). Este prezentat un studiu de caz numeric pentru modelarea și analiza performabilității unui sistem CBHS pentru a demonstra eficacitatea metodei propuse.

Cuvinte cheie: *securitatea sistemelor biomedicale de sănătate în cloud; numere fuzzy; apărare prin ținte mobile; modelare a performanței; reguli de rescriere; rețele Petri stocastice.*

1. Introduction

Cloud-based Biomedical and Healthcare Systems (CBHS) are essential for delivering services that address common challenges associated with biomedical issues [1,2]. At the same time, these services facilitate the sharing and use of biomedical and healthcare resources, improve their efficiency and quality, reduce costs, improve people's health and access to biomedical data. However, the sensitive nature of biomedical healthcare data poses significant challenges to its security and privacy in the CBHS [3-5]. Thus, in addition to the

many advantages of CBHS for our health, they are more vulnerable to cyber-attacks than traditional computer systems.

To tackle this challenge, a new proactive defense strategy known as Moving Target Defense (MTD) has recently been introduced. MTD works by continuously altering the attack surface, thereby interrupting the attacker's reconnaissance efforts [6,7]. This approach increases system complexity and unpredictability, generating asymmetric uncertainty that benefits the defenders and decreases the likelihood of a successful attack. However, transferring CBHS services between cloud Virtual Machines (VMs) requires a finite amount of time, which can delay service execution and negatively impact overall performance.

Performability is the emerged metric to evaluate the ability of a system to function when its system's performances degrade regarding how well it executes its specified functionalities under normal and abnormal conditions in the presence of system failures, vulnerabilities and security threats and intruders' attacks [8]. In this article, we will often use the term performability as synonym of the security term, one of the well-known performability metrics.

In this context, there is a need to evaluate and analyze the impact of using an MTD technique for CBHS defense on the specified performability metrics under uncertainty. Thus, the CBHS behavior modeling and performability evaluation must be proven by adopting and using some mathematical formalisms. Amongst such formalisms, the Stochastic Reward Nets (SRNs) [9], a variant of stochastic Petri nets, are widely used because they are conceptually easy to understand, graphical in nature and well supported by a large body of theory as well as a large software tool base.

Most of the existing research based on SRN models, focuses only on the evaluation of MTD techniques impact on the system security, but not on investigating the effects considering the potential performance degradation due to the MTD launched in computing systems [6,7]. However, these types of models do not consider the fuzzy epistemic uncertainties related to attacker behavior. Additionally, Stochastic Reward Nets (SRNs) can be challenging to apply in real-world scenarios because the graphical representation of real systems tends to grow rapidly in size. Therefore, it is essential to improve SRNs to enable a more compact and flexible representation of complex CBHS processes, while also allowing for the evaluation of MTD migration policies in terms of system performability.

In this paper, we introduce Matrix Rewriting SRNs (MRSRN) with Fuzzy parameters (FMRSRN) as a suitable approach for modeling and analyzing the uncertainty and performability of CBHS enhanced with time-based MTD techniques. One of the key advantages of using FMRSRN for CBHS modeling is its highly compact and adaptable structure, which allows for easy reconfiguration and dynamic adjustment of quantitative parameters during runtime.

The application of the proposed FMRSRN approach is exemplified by performability modeling and numerical case study analysis of a particular CBHS.

2. Matrix rewriting SRN with fuzzy parameters

A. Epistemic Uncertainty and Fuzzy Numbers

In a complex real system, the accurate evaluation of performability metrics is difficult due to several sources of uncertainties: aleatory that refers to probabilistic variations in a random events, epistemic that comes from lack of knowledge, e.g. inadequate and/or incomplete understanding of the processes, technical restraints, ambiguous information,

imprecise values of input parameters, etc. Therefore, the uncertainty modeling of CBHS behavior can be treated more realistically through FRSRNs that the transition firing rates can be considered as fuzzy numbers. Next, with the goal to facilitate the exposition of the proposed approach, we present some basic elements of fuzzy sets and fuzzy numbers (FN) [10,11] for defining FMRSRN.

A fuzzy subset \tilde{A} of the real numbers set IR is defined by its membership function $\mu_{\tilde{A}} : IR \rightarrow [0, 1]$ which assigns a real number $\mu_{\tilde{A}}$ in the interval $[0, 1]$ to $\forall \tilde{x}$, where the value of $\mu_{\tilde{A}}$ at x shows the grade of membership function of x in \tilde{A} .

The triangular fuzzy numbers (TFN) are often used in real applications. A TFN is described as $\tilde{a} = (a, \delta, \beta)$ where a is the *center*, δ is the *left width*, and β is the *right width*. For arbitrary fuzzy number $\tilde{a} = (a, \delta, \beta)$, the membership function is equal:

$$\mu_{\tilde{a}}(x) = \begin{cases} 1 - (a - x) / \delta, & a - \delta \leq x \leq a, \\ 1 - (x - a) / \beta, & a \leq x \leq a + \beta, \\ 0, & \text{otherwise.} \end{cases}$$

However, a parametric α -cut fuzzy number $\tilde{a} = [a^-(\alpha), a^+(\alpha)]$ can be represented as: $a^-(\alpha) = a - (1 - \alpha)\delta$ and $a^+(\alpha) = a + (1 - \alpha)\beta$.

B. Basic Concepts and Elements of FMRSRN

We assume that readers already have a foundational understanding of the core principles and behavioral rules of SRNs. A thorough theoretical discussion and practical application of this subject fall beyond the scope of this paper. For more in-depth information on SRNs, readers are encouraged to consult reference [9]. In this subsection, we offer a concise overview of the FMRSRN.

Let IN_+ (resp. IR^+) is a pair of *natural* (resp. *positive real*) numbers.

The definition of an FMRSRN is derived according to [12,13] and inherits most of the Rewriting SRN and MRSRN characteristics. Thus, the FMRSRN, denoted Γ_{FR} , is defined as a 14-tuple system such that $\Gamma_{FR} = \langle P, T, R, A_{res}, Pri, G^E, G^R, K^p, \tilde{\lambda}, \tilde{\omega}, \tilde{\rho}, M_0, Lib_R, Lib_{A_s} \rangle$, where: P (resp. T) is a finite set of *places* (resp. *transitions*); R is a finite set of *rewriting rules* about the *run-time structural change (reconfiguration)* of Γ_{FR} net. Let $E = T \cup R$ be a finite set of events, $T \cap R = \emptyset$, $P \cap E = \emptyset$. The set E is partitioned into $E = E_0 \cup E_t$, $E_0 \cap E_t = \emptyset$ so that: E_0 is a set of immediate events and E_t is a set of timed events; $A_{res} = \langle Pre, Post, Inh, Test \rangle$ is a set of *forward, backward, inhibition and test (promoter)* arc functions with respective weight cardinalities; Pri is the dynamic priority function for the *firing* of each *enabled* event. By default, $Pri(E_0) > Pri(E_t)$; $G^E : E \times IN_+^{|P|} \rightarrow \{True, False\}$ (resp. $G^R : R \times IN_+^{|P|} \rightarrow \{True, False\}$) is the set of *guard function* associated with all event $e \in E$ (resp. *rewriting rule* $r \in R$); $K^p : P \times IN_+^{|P|} \rightarrow IN_+ \cup \{\infty\}$ is the capacity bound of each place, which can contain an *integer* number of *tokens*; M_0 is the initial marking; $\tilde{\lambda} : E_t \times IN_+^{|P|} \rightarrow IR^+$ is the function that determines the fuzzy firing rate $0 < \tilde{\lambda}(e, M) < +\infty$ of timed event $e \in E_t$, that is *enabled* by the current marking M ; $\tilde{\omega} : E_0 \times IN_+^{|P|} \rightarrow IR^+$ is the fuzzy weight function $0 \leq \omega(e, M) < +\infty$ which determines the firing fuzzy probability $\tilde{q}(t, M)$ of immediate event $e \in E_0$, therein describe an probabilistic selector; $\tilde{\rho} : P \cup E \rightarrow IR^+$ is the function that determines the fuzzy *reward rates* (real numbers) assigned to each current marking M and to each firing event $e \in E$; Lib_R (resp. Lib_{A_s}) is the set of $R\Gamma_v \in Lib_R$, (resp. $Attr_i \in Lib_{A_s}$) *subnets* (resp. *attributes*) pattern class library involved in *structural reconfiguration* of the current Γ_{FR} by firing of an

enabled rewriting rule $r \in R$. In Γ_{FR} and $R\Gamma_v \in Lib_R$ nets the *quantitative attributes* can be specified as dependent on the current marking of the configured nets. Also, by default: $K^p(p_i)$ is unlimited and $g_e^E(M) = g_r^R(M) := True$.

In Γ_{FR} models, the attributes of net elements (arc cardinalities, places capacities, guard functions and event priorities, rewriting rules, firing rates, etc.) are matrix of the specified z type that are defined by a set of matrix $A^z = [a_{ij}^z(s)]_{k \times n} \in \mathbf{A}$. The quantitative values attributes may be constant or marking-dependent functions of the specified type. The current activated element $a_{ij}^z(s)$ is specified by a set $P_A^z \subset P$ of net *control places*. For example, for the selection of current elements position in A^z , two control places should be specified. Therefore, the current number of tokens $i = m_i = M(p_i)$ and $j = m_j = M(p_j)$ in control places p_i and p_j shows the *position* of the respective element of A^z , and its values must be *imported* and taken into account when executing and analyzing the model [13].

Graphically, a matrix attribute of Γ_{FR} will be presented in a way that it will contain the matrix name in square brackets, i.e. $[A^z]$ (for details see Figure 3).

Figure 1 summarizes the graphical representation of FMRSRN structural elements features.

Enabling and firing rules of events $e \in E$ by current marking M in Γ_{FR} are the same as for MRSRN [12, 13].

We only note that the dynamic reconfiguration of current Γ_{FR} by firing of enabled $r \in R$, if $g_r^R(M) := True$ is a map $r := \{RN_L, Atr_L\} \triangleright \{RN_W, Atr_W\}$, where $\{RN_L \in Lsp_{RN}, Atr_L \in Lsp_{Atr}\}$ (resp. $\{RN_W \in Lsp_{RN}, Atr_W \in Lsp_{Atr}\}$) is the *left-hand* (resp. *right-hand*) side of the binary *rewriting operator* \triangleright assigned to $r \in R$, respectively. The execution of \triangleright produce a *structural change* and/or *attributes* in current Γ_{FR}' by replacing (*rewriting*) the specified subnet $\{RN_L, Atr_L\} \subseteq \Gamma_{FR}'$ (RN_L and Atr_L are deleted) and a new $\{RN_W, Atr_W\} \in Lib_R$ are added belongs to the new resulting $\Gamma_{FR}'' = (\Gamma_{FR}' \setminus RN_L) \cup RN_W$ net, where the meaning of \setminus (and \cup) is *operation of removing* (resp. *adding*) RN_L (resp. RN_W) *from* (resp. *to*) Γ_{FR}' (resp. $\Gamma_{FR}' \setminus RN_L$). The places, events and arcs, which have the same names, that belong to RN_W and $\Gamma_{FR}' \setminus RN_L$ are *fused*, respectively [12].

But, if $g_r^R(M) := False$ then only the current M marking will change to another M' marking, i.e. $M[r > M'$ and the structure of Γ_{FR}' remains the same.

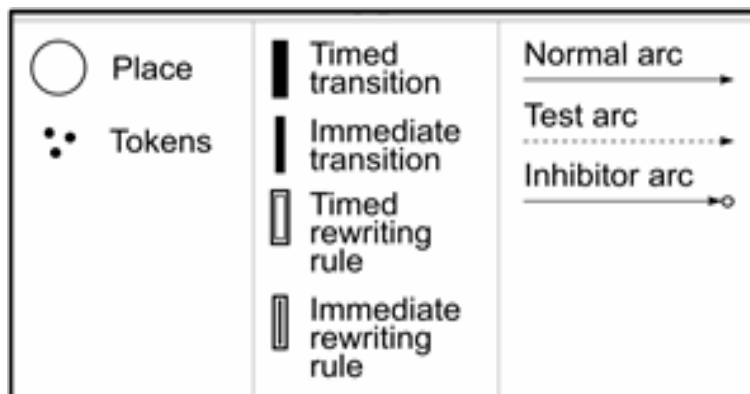


Figure 1. The structural elements features of Γ_{FR} models.

But, if $g_r^R(M) := False$ then only the current M marking will change to another M' marking, i.e. $M[r > M'$ and the structure of $\Gamma_{FR'}$ remains the same.

3. Performability modeling case study

A. Informal Description of Attacked CBHS

In this section, we will demonstrate the application of the FMRSRN for performability modeling of a particular CBHS1. For this one, we will consider the cloud biomedical healthcare system to be subject to intrusion-based attacks, where the attacker or intruder must first discover the vulnerabilities of this target system to perform the attack, being identified as the *attack surface*. In this case, the intruder will select the target node of the CBHS1 and try to identify vulnerabilities in its network (*reconnaissance stage*), then, if successful, he will create a remote access weapon (malware, such as a virus or worm) depending on the discovered vulnerabilities, it will transmit the weapon to the target through some means: USB drives; email attachments; websites, etc. (*delivery stage*). In this way, the malware starts working by acting on the target VM to exploit the vulnerability through: program code triggers (*exploit stage*); installing an access point for the intruder (*installation stage*); persistent access and control of the target VM (*command and control*); performing attacks such as exfiltrating or destroying data, encrypting for ransom, and so on (*target actions stage*).

Biomedical services are running on a CBHS1 platform, composed of n nodes (VMs), can randomly migrate between nodes according to a migration based MTD technique, triggered by a *timer* with a probabilistic or deterministic time period. As a result, the service may migrate to another node, but the attacker may remain on the same node. Also, we consider that the attacker adopts a try-and-error approach. Thus, the probability of a successful attack increases as long as the attacker remains within a certain physical machine pool. We will approximate this increasing probability with the FRSRN subnets that describe the k -phase Cox (resp. *hypoexponential* or *Erlang*) distribution of the attack time periods.

B. FMRSRN Security Model of CBHS Under MTD

Figure 2 shows the proposed FMRSRN model, denoted Γ_{FR1} , which describes the behavior of the attacker and the defender of CBHS1 using *time-based* MTD strategies [10, 11], that give a compact structural representation and at the same time to address the problem of state space explosion [9].

The places, transitions and rewriting rules description (meaning) of Γ_{FR1} model are:

- **Places.** p_1 - attacker selected of the target node; p_2 - intruder has access to the target node, after injecting a malware and then activating it, i. e. the exploit stage; p_3 - intruder's malware tries to attack the system through various methods; p_4 - attack success, the intruder acting on the data (exfiltration, corruption, etc.); p_5 - attacker is on the node where the service is running; p_6 - intruder attack on one of the remaining $(n-1)$ nodes without service; p_7 - time migration to each other different $(n-1)$ nodes; p_8 - normal operating condition of a service; p_9 - start migration latency; p_{14} - potential task numbers to be processed; p_{15} - tasks waiting queue to be processed; p_{16} - one current task is in serving process (execution); p_{17} - current service node is not busy.

• **Timed transitions.** t_3 - period of time during which the attacker will perform desired actions; t_4 - intruder abandon the current attack and sets another target node; t_5 - attack time; t_6 - timer with time interval between submitting node migration requests to the environment; t_7 - migration time; t_{19} - service time of current task.

• **Immediate transitions.** t_8 - migration of the service to a on one of $(N-2)$ safe nodes; t_9 - migration of the service to a nod under attack; t_{10} - restart of timer; t_{18} - start of task service process. The firing of transition t_9 , with $q(t_9, M) = 1/(n-1)$ probability, leads to the migration of the service to a node under attack or on one of $(n-2)$ safe nodes by firing of t_8 with the probability $q(t_8, M) = (n-2)/(n-1)$. In these two cases, after the service is migrated, the timer starts again.

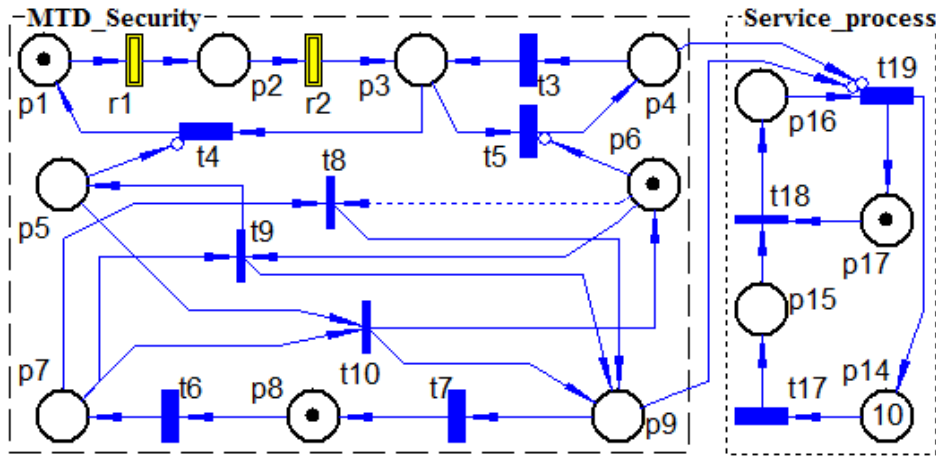


Figure 2. The Γ_{FR1} performability model of an CBHS1.

• **Timed rewriting rules.** r_1 (resp. r_2) – substitution of t_5 by the Γ_{cox-k_t5} subnet of Fig. 3a (resp. $\Gamma_{hypo\exp-k_t5}$ subnet of Fig. 3b) after the expiration of the time period that indicate the mean time required to *exploit* (resp. to *infect*) a target node. The *firing* of r_1, r_2 in Γ_{FR1} occurs if intruder has access to the target node, after injecting a malware and: $g^E(r_2) := (M(p_2) = 1), g^G(r_1) := "True "$ and $g^G(r_2) := "False "$.

A dynamic reconfiguration of Γ_{FR1} by the firing of enabled r_1 is a map:

$$r_1 := \{t_5, g^G(r_1) := "True " \} \triangleright \{g^G(r_1) := "False ", \Gamma_{cox-k_t5}\} \text{ OR } r_1 := \{t_5, g^G(r_1) := "True " \} \triangleright \{g^G(r_1) := "False ", \Gamma_{hypo\exp-k_t5}\}.$$

The rewriting operator \triangleright represents a binary operation which produces a *structural change* in Γ_{FR1} by *replacing* the current subnet $R_{\Gamma_L} \subseteq \Gamma_{FR1}$ (R_{Γ_L} is removed) and a new $R_{\Gamma_j}^w \in Lib_R$ subnet is *added* and *belongs* to the *new modified resulting net* $\Gamma_{FR1}' = (\Gamma_{FR1} \setminus R_{\Gamma_L}) \cup R_{\Gamma_j}^w$, where the meaning of \setminus (resp. \cup) is operation of *removing* (resp. *adding*) R_{Γ_L} from ($R_{\Gamma_j}^w$ to) Γ_{FR1} . **As example,** in our case $R_{\Gamma_L} := \{t_5, g^G(r_1) := "True " \}$. For more detail to using of the rewriting rule \triangleright operator see [12].

Note that when the firing of enabled r_1 this rewriting rule will only change the current marking of Γ_{FR1} , because $g^G(r_2) := "False "$. If $g^G(r_2) := "True "$ it is necessary to specify the \triangleright operator with the corresponding subnets, i.e. $r_2 := \{R_{\Gamma_L} \} \triangleright \{R_{\Gamma_j}^w \}$.

The places and transitions meaning of Γ_{cox-k_t5} (resp. $\Gamma_{hypo\exp-k_t5}$) subnet are:

• **Places.** p_{10} - current number of phases what must be executed; p_{11} - finishing the execution of a current phase; p_{12} - allowing time period execution with phase-type distribution; p_{13} - completion of the phase-type time period; p_{14} -memory of the executed phase (current attack progress).

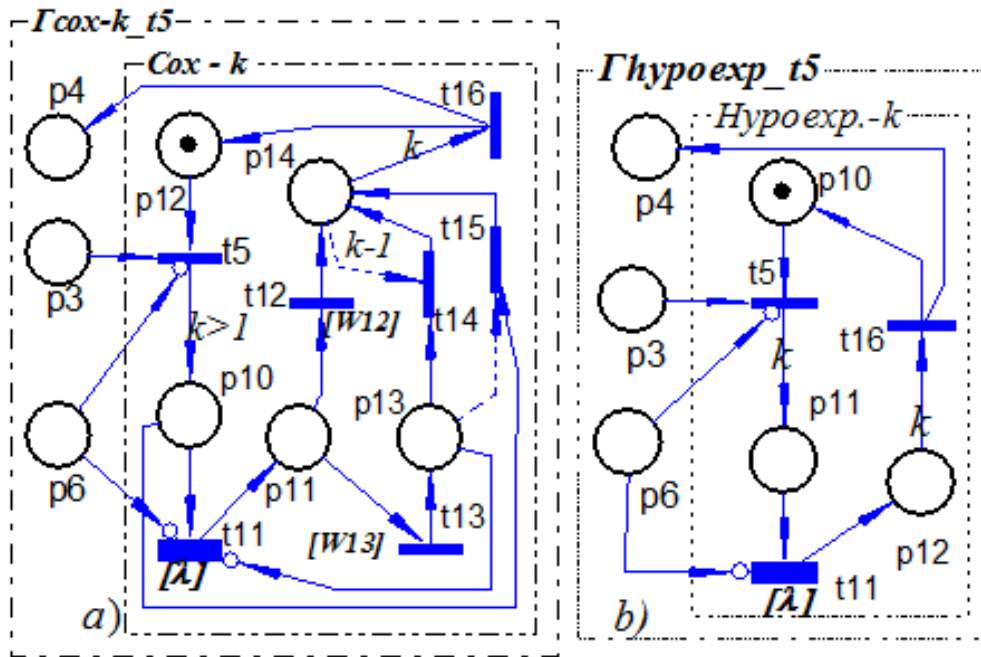


Figure 3. The Γ_{FR1} subnets: a) Γ_{cox-k_t5} ; b) $\Gamma_{hypoexp-k_t5}$

• **Timed transitions.** t_{11} - processing the current phases time with a selected $\lambda_{1,j} \in [\lambda]$, $j=1,2,\dots,k$ rate, where $[\lambda]$ is a matrix.

• **Immediate transitions.** t_5 - start execution of the time period with the respective phase type distribution; t_{12} - selecting the next processing phase with probability $q_{12,j}$, ($j=1,2,\dots,k$), determined by the weight $w_{12,j} \in [W12]$, where $[W12]$ is a matrix; t_{13} - firing with probability $q_{13,j}$, ($j=1,2,\dots,k-1$), determined by the weight $w_{13,j} \in [W13]$, indicates that the attack time period is over after the execution of phase j . The $[W12]$ is a matrix; t_{14} and t_{15} - are used for reset of phase distribution time-out; t_{16} - denotes that the attacker successfully compromised target node.

The k number of phases in these sub-nets (see Figure 3) is determined by the weights of respective arcs: $(t_5, p_{10}), (p_{12}, t_{16}), (t_5, p_{10}), (p_{14}, t_{14})$ and (p_{14}, t_{16}) .

Note that at firing of rewriting rule r_1 in Γ_{FR1} the places p_3, p_4 and p_6 of Γ_{FR1} net and Γ_{cox-k_t5} (resp. $\Gamma_{hypoexp-k_t5}$) subnet, that have the same name, will merge accordingly.

C. Performability Analysis Case Study

Performability analysis of Γ_{FR1} model can be done following the approach described in [10-12]. The Γ_{FR1} model is bounded, live and reversible [9], therefore there it exists a stationary behavior regime of the analyzed CBHS1.

Next, we will present a numerical case study of Γ_{FR1} that show an application of the proposed approach. In this context, we will consider a particular case where the t_7 timed

transition is an immediate transition, and the number of phases in the Γ_{Cox-k_t5} subnet is equal to 2.

We adopt an exponentially firing delay of all timed transitions with mean value $\bar{\tau}_i = 1/\lambda_i$ hours.

For the numerical evaluation of some performability metrics, based on parameter values taken from Chen et al. [14] parameters, we have used the VPNP tool [15].

Next, due to space constraint, we evaluate the impacts of λ_6 , $\tilde{\lambda}_{r1}$ and n parameters on average availability and average throughput based on the Γ_{FR1} model.

System availability is the $\pi_{Av.}$ probability that no token will be present in the $p4$ and/or $p9$ places, i.e. that the service of system is secure: $\pi_{Av.} = \Pr(M(p4)=0 \vee M(p9)=0) = 1 - \pi_{Suc.}$, where $\pi_{Suc.} = \Pr(M(p4)=1 \vee M(p9)=1)$ is the attack success probability.

We compute the $\pi_{Av.}(\lambda_6)$ and $\pi_{Av.}(n)$ metrics of $MTD_Security$ model depending on the λ_6 and n parameters. For this, we use the following crisp values: firing delay of $t7$ is assumed to have a Cox-2 distribution with mean time hours $\bar{\mu}=2$ and the coefficient of variation $K^v=4$; the firing rates of timed transitions are: $\lambda_{r2}=1, \lambda_3=5, \lambda_4=8, \lambda_{11,1}=1, \lambda_{11,2}=0.125$; the firing probabilities of immediate transitions are: $q_{10}=(n-2)/(n-1), q_9=1/(n-1), q_{12}=0.25, q_{13}=0.75$.

As well, we consider two options: the first $\lambda_{r1}=0.04$ is a crisp value; the second case where this parameter has triangle fuzzy values, namely $\tilde{\lambda}_{r1}=(0.01, 0.04, 0.07)$.

Figure 4a (resp. Figure 4b) shows the graphical representation of the $\pi_{Av.}(\lambda_6)$ (resp. $\pi_{Av.}(n)$) average availability variation, depending on the λ_6 (resp. n) parameter, for which $n=3$ (resp. $\lambda_6=3$) is considered a crisp value.

The computing result of $\pi_{Av.}(\lambda_6)$ (see Fig. 4a) for $\lambda_6=0.1$ (resp. $\lambda_6=2$) we obtain $\pi_{Av.}^{\min}(\lambda_6)=0.9841$ (resp. $\pi_{Av.}^{\max}(\lambda_6)=0.9946$). Also, the computing result of $\pi_{Av.}(n)$ (see Fig. 4b) for $n=3$ (resp. $n=100$) we obtain $\pi_{Av.}^{\min}(n)=0.9875$ (resp. $\pi_{Av.}^{\max}(n)=0.9998$)

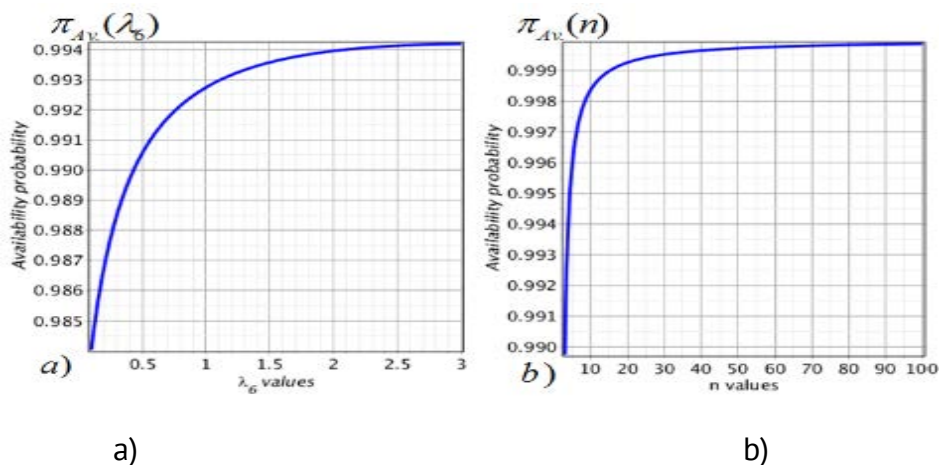


Figure 4. Computing results for average availability probability $\pi_{Av.}$: a) $\pi_{Av.}$ depending of λ_6 ; b) $\pi_{Av.}$ depending of n .

Similarly, we will evaluate the fuzzy average availability system variation, considering it to be a function that depends on the parameters λ_6 and $\tilde{\lambda}_{r1}$. This metric, denoted $\tilde{\pi}_{Av.}(\lambda_6, \tilde{\lambda}_{r1})$, was

performed for the case: $n = 3$, $\lambda_6 \in [0.1, 3]$ and $\tilde{\lambda}_{r1} = (0.01, 0.04, 0.07)$ is a triangle fuzzy number, and the other parameters have values that were considered in the previous case.

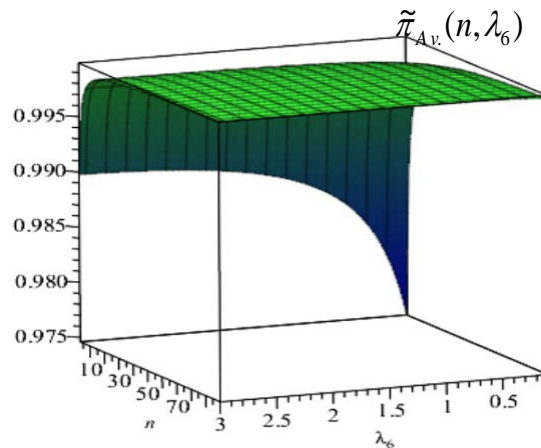


Figure 5. The evolution of $\pi_{Av.}$ function depending of n and λ_6 values.

Expressed $\tilde{\lambda}_{r1}$ in terms of α -cut we have [10]: $\tilde{\lambda}_{r1}(\alpha) = [0.04 - 0.03 \cdot (1 - \alpha), 0.04 + 0.03 \cdot (1 - \alpha)]$.

For these $\tilde{\lambda}_{r1}(\alpha)$ fuzzy parameters, the evaluation of $\tilde{\pi}_{Av.}(\lambda_6, \alpha) = [\pi_{Av.}^-(\lambda_6, \alpha), \pi_{Av.}^+(\lambda_6, \alpha)]$ in α -cut are obtained based on the methods presented in [10].

Since $\forall 0 < \tilde{\pi}_i(\alpha) < 1$, therefore the $\tilde{\lambda}_{r1}(\alpha)$ is applicable to the $0 \leq \alpha \leq 1$ interval. Thus, we can perform the variation of $\tilde{\pi}_{Av.}(\lambda_6, \alpha) = [\pi_{Av.}^-(\lambda_6, \alpha), \pi_{Av.}^+(\lambda_6, \alpha)]$ that depends of the λ_6 and α crisp values.

In the same context, Figure 5 plots the evolution results of $\pi_{Av.}(n, \lambda_6)$ that depend on the simultaneous variation of the n and λ_6 values.

Also, Figure 6 displays the $\tilde{\lambda}_{19}(\lambda_6, \alpha)$ fuzzy average availability probability variation, depending of the λ_6 and α -cut, respectively. Thus, for $\lambda_6 = 2$ it is obtained: $[\pi_{Av.}^-(\lambda_6, 0) = 0.9899, \pi_{Av.}^+(\lambda_6, 0) = 0.8939]$; $\pi_{Av.}^-(\lambda_6, 1) = \pi_{Av.}^+(\lambda_6, 1) = 0.9632$

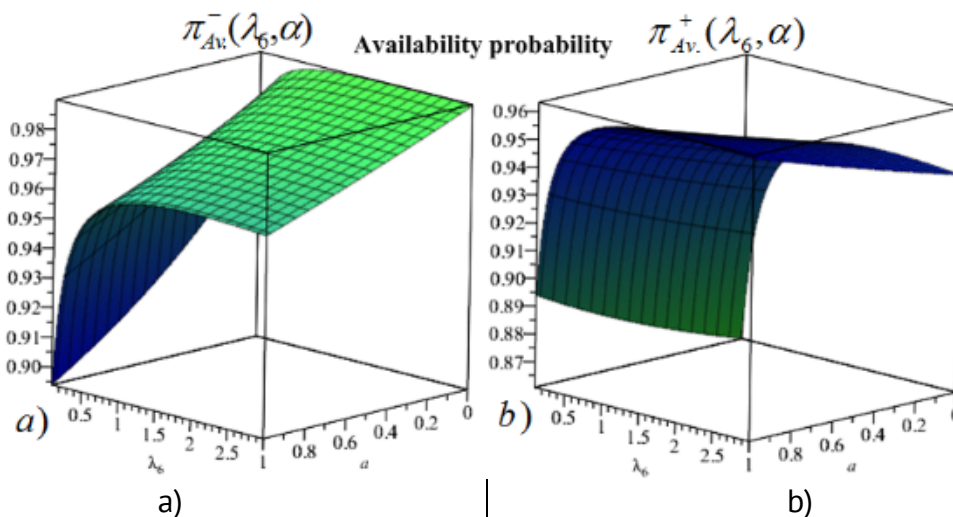


Figure 6. The fuzzy average availability variation: a) $\pi_{Av.}^-$ depending of λ_6 and α -cut; b) $\pi_{Av.}^+$ depending of λ_6 and α -cut.

Figure 7 depicts how the impact of the uncertainty on the $\lambda_{r,1}$ rate and variation value of λ_6 rate affects the $\tilde{\lambda}_{19}(\lambda_6, \alpha)$ fuzzy throughput of CBHS1 that measure of how many tasks can be processed in a given amount of time.

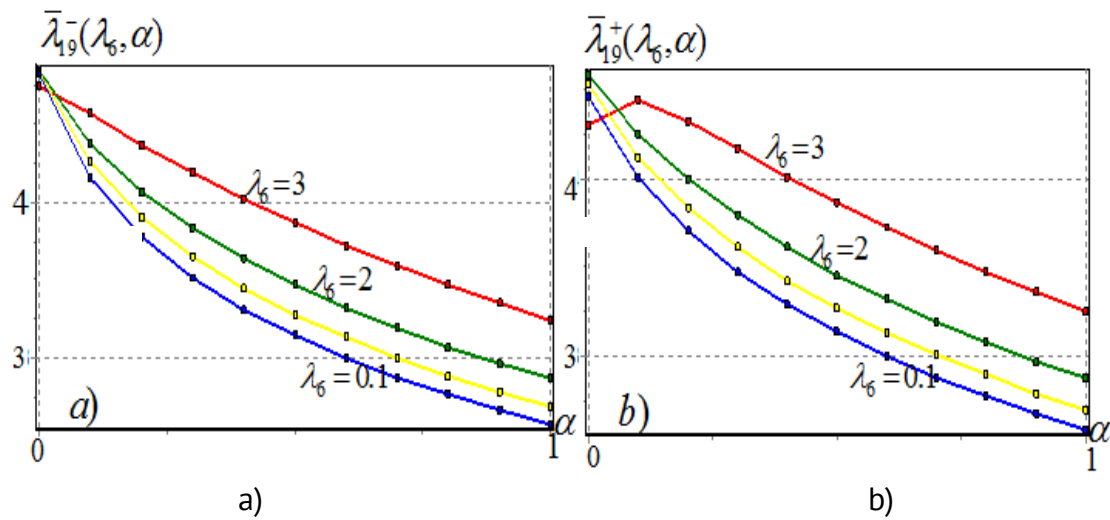


Figure 7. The fuzzy throughput of CBHS1: a) $\bar{\lambda}_{19}^-$ depending of λ_6 and α -cut ; b) $\bar{\lambda}_{19}^+$ depending of of λ_6 and α -cut .

For the case that $\lambda_6 = 3$ and $\lambda_{19} = 5$ it is obtained: $\tilde{\lambda}_{19}(\lambda_6, 0) = [\bar{\lambda}_{19}^-(\lambda_6, 0) = 4.8270, \bar{\lambda}_{19}^+(\lambda_6, 0) = 4.4660]$;
 $\tilde{\lambda}_{19}(\lambda_6, 1) = [\bar{\lambda}_{19}^-(\lambda_6, 1) = 2.5800, \bar{\lambda}_{19}^+(\lambda_6, 1) = 2.5800]$.

4. Conclusions

The proposed in this article modeling approach based on Matrix Rewriting Stochastic Reward Nets with Fuzzy parameters is highly scalable, flexible and customizable through several crisp and fuzzy parameters. It also allows to stochastically characterize the underlying behaviors and phenomena with epistemic uncertainties through phase type distributions, obtaining steady-state average availability and performance metrics of CBHSs with other practical D techniques.

As future work, we plan to investigate the *trade-offs* between security, availability, cost and performance of CBHSs when different MTD techniques are applied. Also, we will focus on developing a software system incorporate into VNP Tool with a friendly interface for checking behavioral properties and performability analysis of FMRSRN models.

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